EST 100	ENGINEERING MECHANICS	CATEGORY	L	T	P	CREDIT	Year of Introduction
		ESC	2	1	0	3	2019

Preamble: Goal of this course is to expose the students to the fundamental concepts of mechanics and enhance their problem-solving skills. It introduces students to the influence of applied force system and the geometrical properties of the rigid bodies while stationary or in motion. After this course students will be able to recognize similar problems in real-world situations and respond accordingly.

Prerequisite: Nil

Course Outcomes: After completion of the course the student will be able to:

CO 1	Recall principles and theorems related to rigid body mechanics
CO 2	Identify and describe the components of system of forces acting on the rigid body
CO 3	Apply the conditions of equilibrium to various practical problems involving different force system.
CO 4	Choose appropriate theorems, principles or formulae to solve problems of mechanics.
CO 5	Solve problems involving rigid bodies, applying the properties of distributed areas and masses

Mapping of course outcomes with program outcomes (Minimum requirement)

	PO 1	PO 2	PO 3	PO 4	PO 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12
CO 1	2	2	-	-	-	-	-	-	-	-	-	-
CO 2	3	3	-	-	-	-	-	-	-	-	-	-
CO 3	3	3	-	-	-	-	-	-	-	-	-	-
CO 4	3	3	-	-	-	-	-	-	-	-	-	-
CO 5	3	3	-	-	-	-	-	-	-	-	-	-

Assessment Pattern

Bloom's Category	Continuous Assessment Tests		End Semester Examination (Marks)
	Test 1 (Marks)	Test 2 (Marks)	
Remember	10	10	15
Understand	10	10	15
Apply	30	30	70
Analyse			
Evaluate			
Create			

Mark distribution

Total Marks	CIE marks	ESE marks	ESE Duration
150	50	100	3 hours

Continuous Internal Evaluation Pattern:

Attendance : 10 marks
Continuous Assessment Test (2 numbers) : 25 marks
Assignment/Quiz/Course project : 15 marks

End Semester Examination Pattern: There will be two parts; Part A and Part B. Part A contain 10 questions with 2 questions from each module, having 3 marks for each question. Students should answer all questions. Part B contains 2 questions from each module of which student should answer any one. Each question can have maximum 2 sub-divisions and carry 14 marks.

Course Level Assessment Questions:

Part A

Course Outcome 1 (CO1): (One question from each module to meet the course objective 1: *To recall principles and theorems related to rigid body mechanics***)**

1. Explain D'Alembert's principle

2. Distinguish static and dynamic friction

3. State and explain perpendicular axis theorem

Course Outcome 2 (CO2) (One question from each module to meet the course objective 2: *To identify and describe the components of system of forces acting on the rigid body***)**

1. A simply supported beam AB of span 5 m is carrying point loads 5 kN, 3 kN and 2 kN at 1m, 3m and 4m respectively from support A. Calculate the support reaction at B.

2. A gymnast holding onto a bar, is suspended motionless in mid-air. The bar is supported by two ropes that attach to the ceiling. Diagram the forces acting on the combination of gymnast and bar

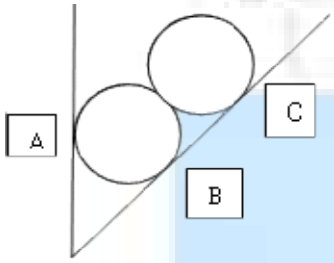
3. While you are riding your bike, you turn a corner following a circular arc. Illustrate the forces that act on your bike to keep you along the circular path ?

Part B

All the questions under this section shall assess the learning levels corresponding to the course outcomes listed below.

CO 3	To apply the conditions of equilibrium to various practical problems involving different force system.
CO 4	To choose appropriate theorems, principles or formulae to solve problems of mechanics.
CO 5	To solve problems involving rigid bodies, applying the properties of distributed areas and masses

1. Two rollers each of weight 100 N are supported by an inclined plane and a vertical wall. Find the reaction at the points of contact A, B, C. Assume all the surfaces to be smooth.

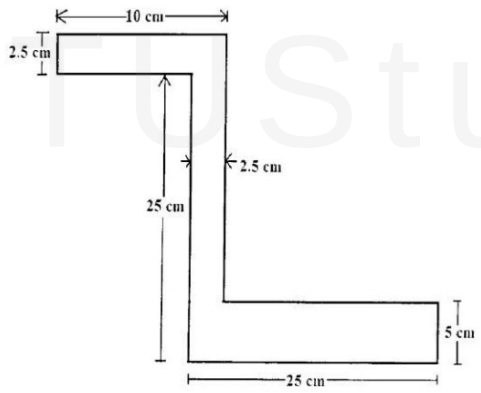


Course outcome identifier	Description of course outcome	Learning level assessed	Marks allocated
CO 3	To apply the conditions of equilibrium to various practical problems involving different force system.	Applying – (Sketch the free body diagram that represent equilibrium state of the body)	4
CO 4	To choose appropriate theorems, principles or formulae to solve problems of mechanics.	Applying (Choose the equations and formulae required for calculation)	4
CO 5	To solve problems involving rigid bodies, applying the properties of distributed areas and masses	Applying (Solve the problem based on the descriptions given in CO3 and CO4)	6
Total			14

2. A cylindrical disc, 50 cm diameter and cm thickness, is in contact with a horizontal conveyor belts running at uniform speeds of 5 m/s. Assuming there is no slip at points of contact determine (i) angular velocity of disc (ii) Angular acceleration of disc if velocity of conveyor changes to 8 m/s. Also compute the moment acting about the axis of the disc in both cases.

Course outcome identifier	Description of course outcome	Learning level assessed	Marks allocated
CO 3	To apply the conditions of equilibrium to various practical problems involving different force system.	Applying – (Sketch the free body diagram that represent state of the body)	4
CO 4	To choose appropriate theorems, principles or formulae to solve problems of mechanics.	Applying (Choose the equations and formulae required for calculation)	4
CO 5	To solve problems involving rigid bodies, applying the properties of distributed areas and masses	Applying (Solve the problem based on the descriptions given in CO3 and CO4)	6
Total			14

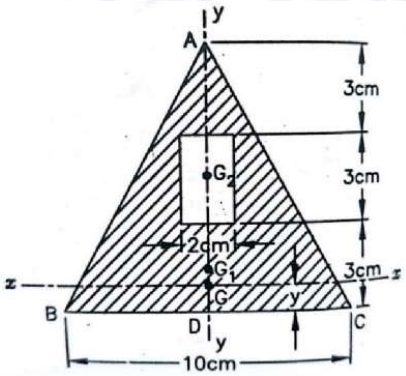
3. Determine the centroid of the given section



Course outcome identifier	Description of course outcome	Learning level assessed	Marks allocated
CO 3	To apply the conditions of equilibrium to various practical problems involving different force system.	Applying – (Illustrate the computation of centroid for the given geometrical shape)	4
CO 4	To choose appropriate theorems, principles or formulae to solve problems of mechanics.	Applying (Choose the equations and formulae required for calculation)	4
CO 5	To solve problems involving rigid bodies, applying the properties of distributed	Applying (Solve the problem based on the descriptions	6

	areas and masses	given in CO3 and CO4)	
Total			14

4. A rectangular hole is made in a triangular section as shown. Find moment of inertia about the section x-x passing through the CG of the section and parallel to BC.



Course outcome identifier	Description of course outcome	Learning level assessed	Marks allocated
CO 3	To apply the conditions of equilibrium to various practical problems involving different force system.	Applying – (Illustrate the computation of moment of inertia for the given geometrical shape)	4
CO 4	To choose appropriate theorems, principles or formulae to solve problems of mechanics.	Applying (Choose the equations and formulae required for calculation)	4
CO 5	To solve problems involving rigid bodies, applying the properties of distributed areas and masses	Applying (Solve the problem based on the descriptions given in CO3 and CO4)	6
Total			14

Model Question Paper

QP CODE:

Reg No.:_____

Name:_____ ___

APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY FIRST SEMESTER B.TECH DEGREE EXAMINATION, MONTH & YEAR

Course Code: EST 100

ENGINEERING MECHANICS

Max. Marks: 100 Duration: 3 hours

Part A

(Answer all questions; each question carries 3 marks)

1. Explain D'Alembert's principle

2. Distinguish static and dynamic frictioni.

3. State and explain perpendicular axis theorem.

4. A simply supported beam AB of span 5 m is carrying point loads 5 kN, 3 kN and 2 kN at 1m, 3m and 4m respectively from support A. Calculate the support reaction at B.

5. A gymnast holding onto a bar, is suspended motionless in mid-air. The bar is supported by two ropes that attach to the ceiling. Diagram the forces acting on the combination of gymnast and bar

6. While you are riding your bike, you turn a corner following a circular arc. Illustrate the forces that act on your bike to keep you along the circular path ?

7. Compare damped and undamped free vibrations.

8. State the equation of motion of a rotating rigid body, rotating about its fixed axis.

9. Illustrate the significance of instantaneous centre in the analysis of rigid body undergoing rotational motion.

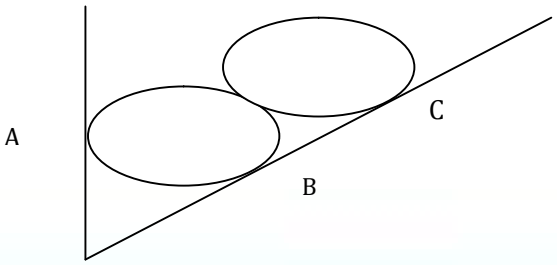
10. Highlight the principles of mechanics applied in the evaluation of elastic collusion of rigid bodies.

PART B

(Answer **one full** question from each module, each question carries **14** marks)

Module -I

11. Two identical rollers each of weight 100 N are supported by an inclined plane, making an angle of 30^{o} with the vertical, and a vertical wall. Find the reaction at the points of contact A, B, C. Assume all the surfaces to be smooth. (14 marks)

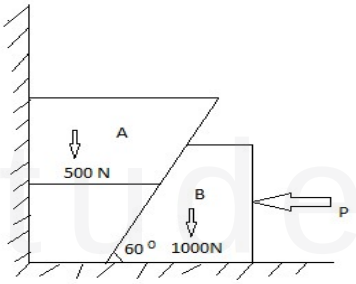


12. A string tied to a wall is made to pass over a pulley placed 2m away from it. A weight P is attached to the string such that the string stretches by 2m from the support on the wall to the location of attachment of weight. Determine the force P required to maintain 200 kg body in position for $\theta = 30^{o}$, The diameter of pulley B is negligible. (14 marks)

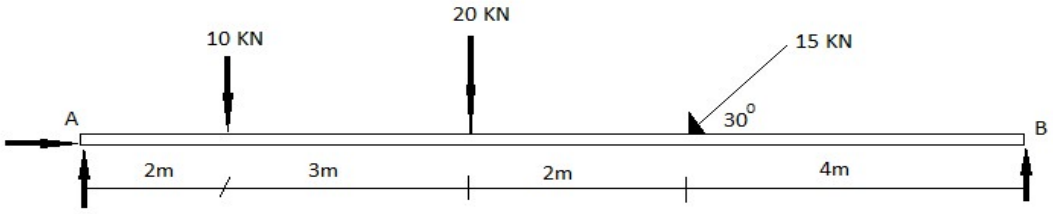
Module – 2

13. Two blocks A & B are resting against a wall and the floor as shown in figure below. Find the value of horizontal force P applied to the lower block that will hold the system in equilibrium. Coefficient of friction are : 0.25 at the floor, 0.3 at the wall and 0.2 between the blocks.

(14 marks)

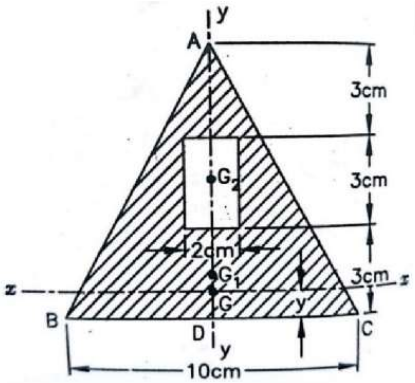


14. A beam is hinged at A and roller supported at B. It is acted upon by loads as shown below. Find the reactions at A & B. (14 marks)

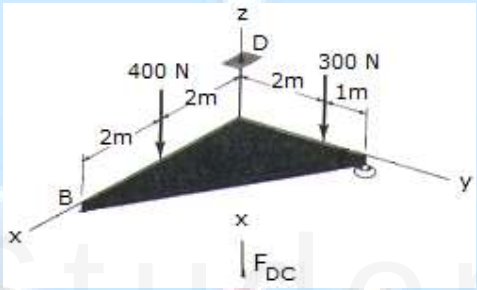


Module – 3

15. A rectangular hole is made in a triangular section as shown. Find moment of inertia about the section x-x passing through the CG of the section and parallel to BC. (14 marks)



16. Support A has ball and socket connection. Roller support at B prevents motion in the —z direction. Corner *C* is tied to *D* by a rope. The triangle is weightless. Determine the unknown force components acting at *A*, *B*, and *C*. (14 marks)



Module - 4

17. A cricket ball is thrown by a fielder from a height of 2m at an angle of 30^0 to the horizontal with an initial velocity of 20 m/s , hits the wickets at a height of 0.5 m from the ground. How far was the fielder from the wicket? (14 marks)

18. An engine of weight 500 kN pull a train weighing 1500 kN up an incline of 1 in 100. The train starts from rest and moves with constant acceleration against a resistance of 5 N/kN. It attains a maximum speed of 36 kmph in 1 km distance. Determine the tension in the coupling between train and engine and the traction force developed by the engine. (14marks)

Module – 5

19. A cylindrical disc, 50 cm diameter and 10 cm thickness having mass of 10 kg, is in contact with a horizontal conveyor belt running at uniform speeds of 5 m/s. Assuming there is no slip at points of contact determine (i) angular velocity of disc (ii) Angular acceleration of disc if velocity of conveyor changes to 8 m/s in 10 seconds. Also compute the moment acting about the axis of the disc in both cases. (14 marks)

20. A wheel rotating about fixed axis at 20 rpm is uniformly accelerated for 70 seconds during which time it makes 50 revolutions. Find the (i) angular velocity at the end of this interval and (ii) time required for the velocity to reach 100 revolutions per minute. (14 marks)

SYLLABUS

Module 1

Introduction to Engineering Mechanics-statics-basic principles of statics-Parallelogram law, equilibrium law, principles of superposition and transmissibility, law of action and reaction(review) free body diagrams.

Concurrent coplanar forces-composition and resolution of forces-resultant and equilibrium equations – methods of projections – methods of moments – Varignon's Theorem of moments.

Module 2

Friction – sliding friction - Coulomb's laws of friction – analysis of single bodies –wedges, ladder-analysis of connected bodies .

Parallel coplanar forces – couple - resultant of parallel forces – centre of parallel forces – equilibrium of parallel forces – Simple beam subject to concentrated vertical loads. General coplanar force system - resultant and equilibrium equations.

Module 3

Centroid of composite areas- – moment of inertia-parallel axis and perpendicular axis theorems. Polar moment of inertia,radius of gyration,mass moment of inertia-ring,cylinder and disc.

Theorem of Pappus Guldinus(demonstration only)

Forces in space - vectorial representation of forces, moments and couples –resultant and equilibrium equations – concurrent forces in space (simple problems only)

Module 4

Dynamics – rectilinear translation - equations of kinematics(review)

kinetics – equation of motion – D'Alembert's principle. – motion on horizontal and inclined surfaces, motion of connected bodies. Impulse momentum equation and work energy equation (concepts only).

Curvilinear translation - equations of kinematics –projectile motion(review), kinetics – equation of motion. Moment of momentum and work energy equation (concepts only).

Module 5

Rotation – kinematics of rotation- equation of motion for a rigid body rotating about a fixed axis – rotation under a constant moment.

Plane motion of rigid body – instantaneous centre of rotation (concept only).

Simple harmonic motion – free vibration –degree of freedom- undamped free vibration of spring mass system-effect of damping(concept only)

Text Books

1. Timoshenko and Young, Engineering Mechanics, McGraw Hill Publishers
2. Shames, I. H., Engineering Mechanics - Statics and Dynamics, Prentice Hall of India.
3. R. C. Hibbeler and Ashok Gupta, Engineering Mechanics, Vol. I statics, Vol II Dynamics, Pearson Education.

References

1. Merriam J. L and Kraige L. G., Engineering Mechanics - Vols. 1 and 2, John Wiley.

2. Tayal A K, Engineering Mechanics – Statics and Dynamics, Umesh Publications

3. Bhavikkatti, S.S., Engineering Mechanics, New Age International Publishers

4. F.P.Beer abd E.R.Johnston (2011), Vector Mechanics for Engineers, Vol.I-Statics, Vol.II-Dynamics, 9th Ed, Tata McGraw Hill

5. Rajasekaran S and Sankarasubramanian G, Engineering Mechanics - Statics and Dynamics, Vikas Publishing House Pvt Ltd.

Course Contents and Lecture Schedule:

Module	Topic	Course outcomes addressed	No. of Hours
1	**Module 1**		**Total: 7**
1.1	Introduction to engineering mechanics – introduction on statics and dynamics - Basic principles of statics – Parellogram law, equilibrium law – Superposition and transmissibility, law of action and reaction (review the topics)	CO1 and CO2	1
1.2	Free body diagrams. Degree of freedom-types of supports and nature of reactions - exercises for free body diagram preparation – composition and resolution of forces, resultant and equilibrium equations (review the topics) - numerical exercises for illustration.	CO1 and CO2	1
1.3	Concurrent coplanar forces - analysis of concurrent forces -methods of projections – illustrative numerical exercise – teacher assisted problem solving.	CO1 and CO2	1
1.4	Analysis of concurrent forces -methods of moment-Varignon's Theorem of Moments - illustrative numerical exercise– teacher assisted problem solving.	CO1 and CO2	1
1.5	Analysis of concurrent force systems – extended problem solving - Session I.	CO3,CO4 and CO5	1
1.6	Analysis of concurrent force systems – extended problem solving - Session II – learning review quiz.	CO3,CO4 and CO5	1
1.7	Analysis of concurrent force systems – extended problem solving - Session III.	CO3,CO4 and CO5	1
2	**Module 2**		**Total: 7**
2.1	Friction – sliding friction - Coulomb's laws of friction – analysis of single bodies –illustrative examples on wedges and ladder-teacher	CO1 and CO2	1

	assisted problem solving tutorials using problems from wedges and ladder.		
2.2	Problems on friction - analysis of connected bodies. illustrative numerical exercise– teacher assisted problem solving.	CO3, CO4 and CO5	1
2.3	Problems on friction-extended problem solving	CO3,C04 and CO5	1
2.4	Parallel coplanar forces – couple - resultant of parallel forces – centre of parallel forces – equilibrium of parallel forces – Simple beam subject to concentrated vertical loads.	CO1 and CO2	1
2.5	General coplanar force system - resultant and equilibrium equations - illustrative examples- teacher assisted problem solving.	CO1 and CO2	1
2.6	General coplanar force system-resultant and equilibrium equations - illustrative examples	CO3, CO4 and CO5	1
2.7	General coplanar force system - Extended problem solving - Quiz to evaluate learning level.	CO3, CO4 and CO5	1
3	**Module 3**		**Total: 7**
3.1	Centroid of simple and regular geometrical shapes – centroid of figures in combination - composite areas- examples for illustration – problems for practice to be done by self.	CO1 and CO2	1
3.2	Moment of inertia- parallel axis theorem –examples for illustration - problems for practice to be done by self.	CO1 and CO2	1
3.3	Moment of inertia - perpendicular axis theorem - example for illustration to be given as hand out and discussion on the solved example.	CO1 and CO2	1
3.4	Solutions to practice problems – problems related to centroid and moment of inertia - problems for practice to be done by self.	CO3, CO4 and CO5	1
3.5	Polar moment of inertia, Radius of gyration. Mass moment of inertia of ring, cylinder and uniform disc. Theorem of Pappus Guldinus - Demonstration	CO1 and CO2	1
3.6	Introduction to forces in space – vectorial representation of forces, moments and couples – simple problems to illustrate vector representations of forces, moments and couples to be done in class.	CO1,and CO2	1
3.7	Solution to practice problems - resultant and equilibrium equations for concurrent forces in space – concurrent forces in space - 2 simple problems to illustrate the application of resultant and equilibrium equations for concurrent forces in space.	CO3,CO4 and CO5	1
4	**Module 4**		**Total: 7**

4.1	Introduction to dynamics – review of rectilinear translation - equations of kinematics – problems to review the concepts – additional problems involving extended application as exercises .	CO1 and CO2	1
4.2	Solutions to exercises with necessary explanation given as hand out – introduction to kinetics – equation of motion – D'Alembert's principle – illustration of the concepts using one numerical exercise from motion on horizontal and inclined surfaces.	CO1 and CO2	1
4.3	Motion of connected bodies - example for illustration to be given as hand out and discussion on the solved example – problems for practice to be done by self.	CO3, CO4 and CO5	1
4.4	Motion of connected bodies-extended problem solving.	CO3, CO4 & CO5	1
4.5	Curvilinear translation - Review of kinematics –projectile motion – simple problems to review the concepts – introduction to kinetics – equation of motion – illustration of the concepts using numerical exercises.	CO3, CO4 & CO5	1
4.6	Extended problem solving – rectilinear and curvilinear translation.	CO3, CO4 & CO5	1
4.7	Concepts on Impulse momentum equation and work energy equation (rectilinear translation – discussions to bring out difference between elastic and inelastic collusions). Concepts on Moment of momentum and work energy equation (curvilinear translation).	CO1 and CO2	1
5	**Module 5**		**Total: 7**
5.1	Rotation – kinematics of rotation- equation of motion for a rigid body rotating about a fixed axis – simple problems for illustration.	CO1 and CO2	1
5.2	Rotation under a constant moment – teacher assisted problem solving.	CO3,CO4 and CO5	1
5.3	Rotation under a constant moment - extended problem solving.	CO3, CO4 and CO5	1
5.4	Plane motion of rigid body- instantaneous centre of rotation (concept only).	CO1 and CO2	1
5.5	Introduction to harmonic oscillation –free vibrations - simple harmonic motion – differential equation and solution. Degree of freedom – examples of single degree of freedom (SDOF) systems – Idealisation of mechanical systems as spring-mass systems (concept only).	CO1 and CO2	1

5.6	SDOF spring mass system –equation of motion – undamped free vibration response - concept of natural frequency. Free vibration response due to initial conditions. Simple problems on determination of natural frequency and free vibration response to test the understanding level.	CO1 and CO2	1
5.7	Free vibration analysis of SDOF spring-mass systems – Problem solving Effect of damping on free vibration response (concept only).	CO1and CO2	1